





#### Stochastic Parametrization and Adjoint Methods:

### Exploring a Toy Problem

MAX TROSTEL

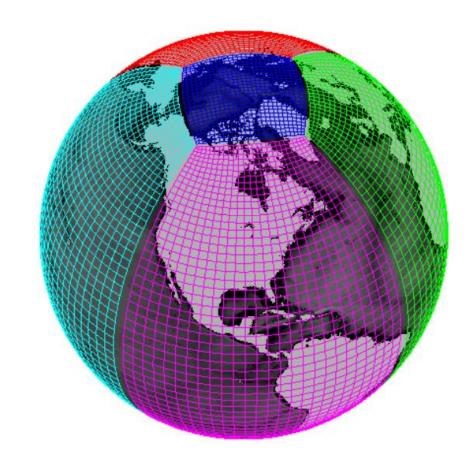
MARCH 22<sup>ND</sup>, 2024

### This talk

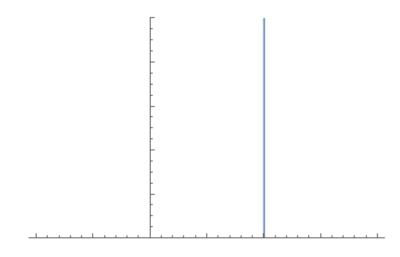
- Why stochastic parametrization?
- A toy problem: the Lorenz 96 2-scale model
- A look ahead

#### Subgrid-scale parametrization

- Approximate effect of the subgrid-scale on the grid-scale
- MITgcm packages:
  - gmredi: Gent-McWilliams/Redi Eddy
     Parameterization
  - Other mixing schemes: KPP, GGL90, KL10

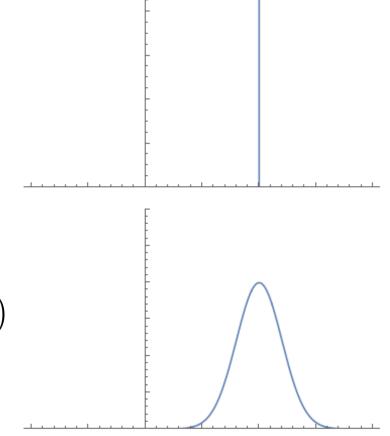


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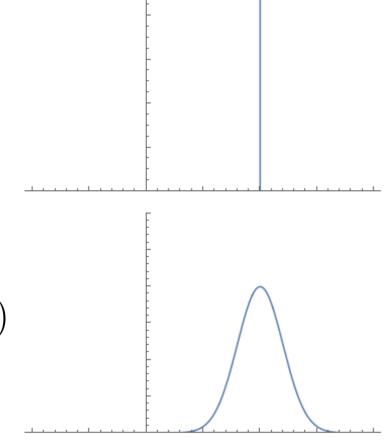


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 (params, state, stats) =  $U_{\text{det}} + e(t, \text{ stats})$ 



- i.e. statistical consistency of data and model
- Realistic variability ⇒ better uncertainty estimates



### Lorenz 96 2-scale model

$$\frac{dX_k}{dt} = -X_{k-1} (X_{k-2} - X_{k+1}) - X_k + F - \frac{hc}{b} \sum_{j=J(k-1)+1}^{kJ} Y_j; \quad k = 1, ..., K$$

$$\frac{dY_j}{dt} = -cb Y_{j+1} (Y_{j+2} - Y_{j-1}) - c Y_j + \frac{hc}{b} X_{\text{int}[(j-1)/J]+1}; \quad j = 1, ..., JK$$

- *K*: number of *X* variables
- *J*: number of *Y* variables per *X* variable
- h: coupling (>0, sets degree of coupling)
- F: forcing (>0, sets degree of driving)
- b: spatial-scale ratio (>1  $\Rightarrow$  large X, small Y)
- c: time-scale ratio (>1  $\Rightarrow$  slow X, fast Y)

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$$-X_k+F$$

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Self-damping/forcing

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Self-damping/forcing Neighbor coupling

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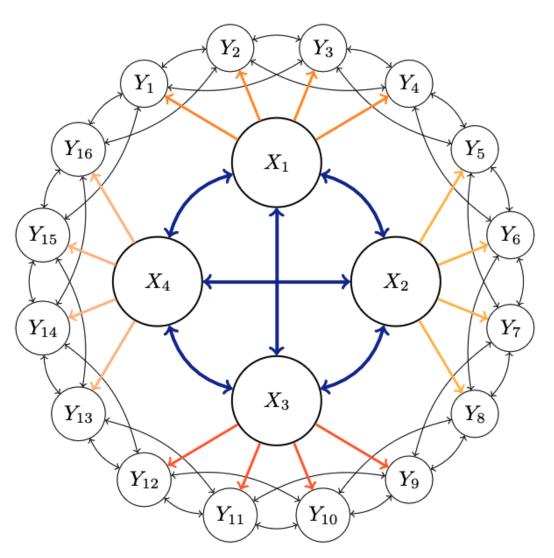
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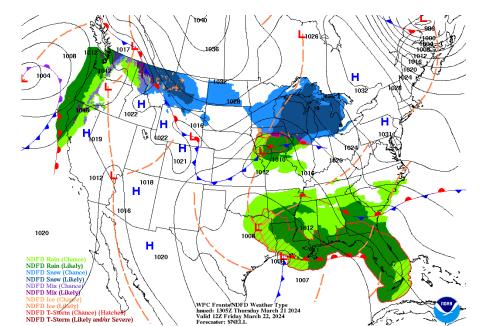
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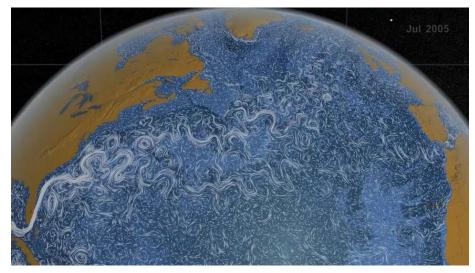


- Created as a toy weather model
  - X: large scale synoptic dynamics (e.g. low pressure system)
  - Y: convective events (e.g. local thunderstorms or showers)
  - Parameter choices yield chaotic X and Y





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  - Parameter choices yield chaotic X and Y
- Could it be a proxy for ocean processes as well?



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  - X: large scale current and gyre dynamics
  - Y: ocean mesoscale eddies
  - Parameter choices yield quasiperiodic X and chaotic Y

#### "Ocean" parameter choices:

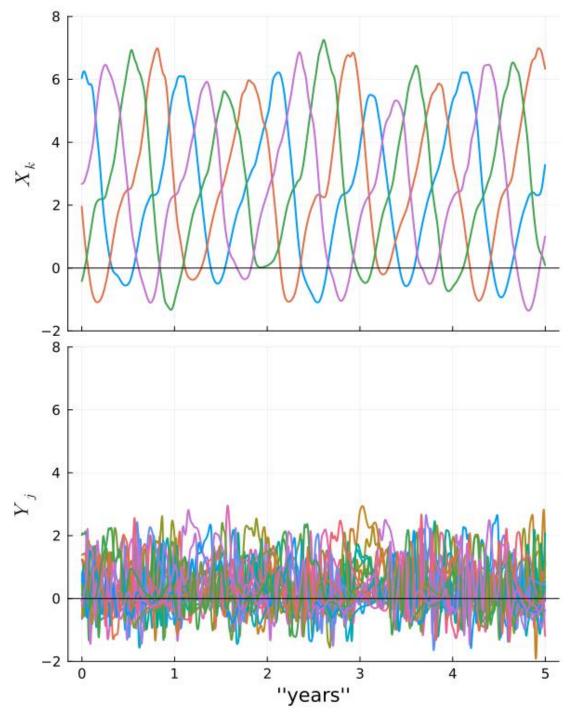
- $K = 4 \Rightarrow 4$  interacting currents
- J = 5  $\Rightarrow$  5 eddy regions per current
- h = 2  $\Rightarrow$  Strong coupling
- F = 10  $\Rightarrow$  Enough to drive oscillations
- $b = 5 \Rightarrow Y$  amplitude 1/5 of X
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#### • The result?

- Quasiperiodic oscillations in X
- Chaos in Y



### Parametrization?

- An approximate *parametrized* model of L96
  - Explicitly model only the  $X_k$
  - Parametrize the effect of the  $Y_j$  on the  $X_k$
  - $X_k$  drive  $Y_j$  dynamics, which in turn affect  $X_k$

$$\frac{dX_k}{dt} = -X_{k-1} \left( X_{k-2} - X_{k+1} \right) - X_k + F - \frac{hc}{b} \sum_{j=J(k-1)+1}^{kJ} Y_j \; ; \quad k = 1, ..., K$$

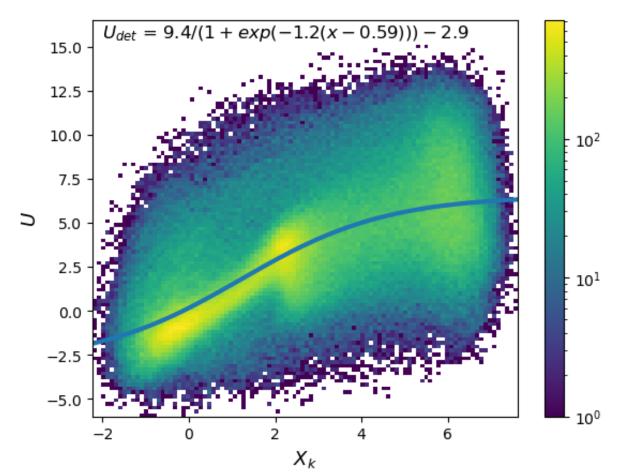
# First guess

• Use full model "data": least squares fit to a logistic curve

$$U_{\det}(X^*) = \frac{L}{1 + e^{-k(X^* - X_0)}} + b$$

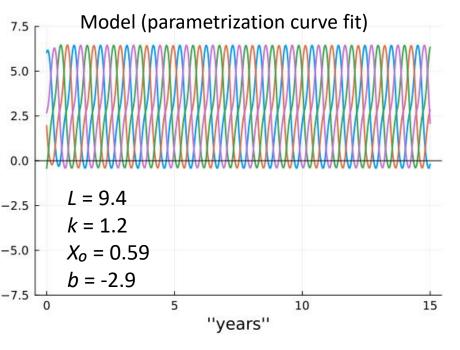
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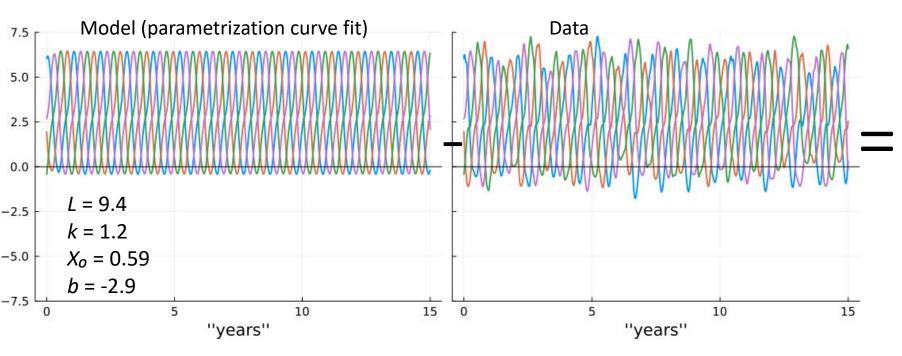
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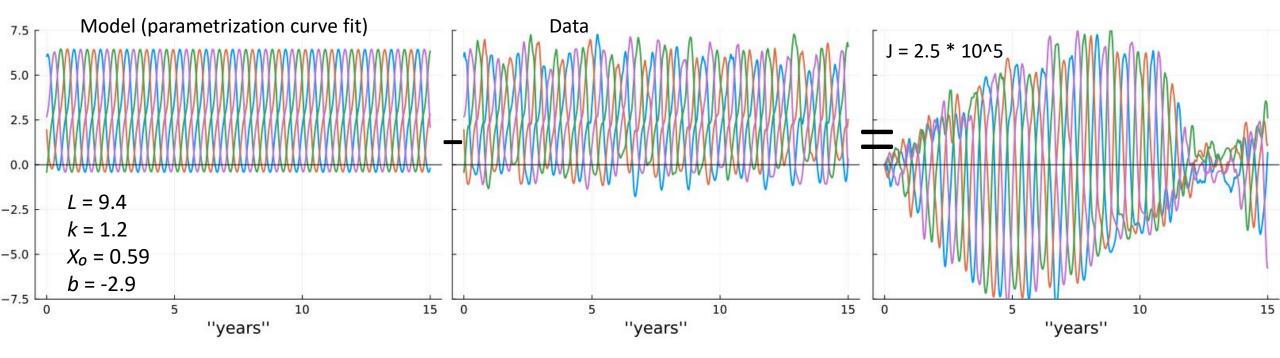


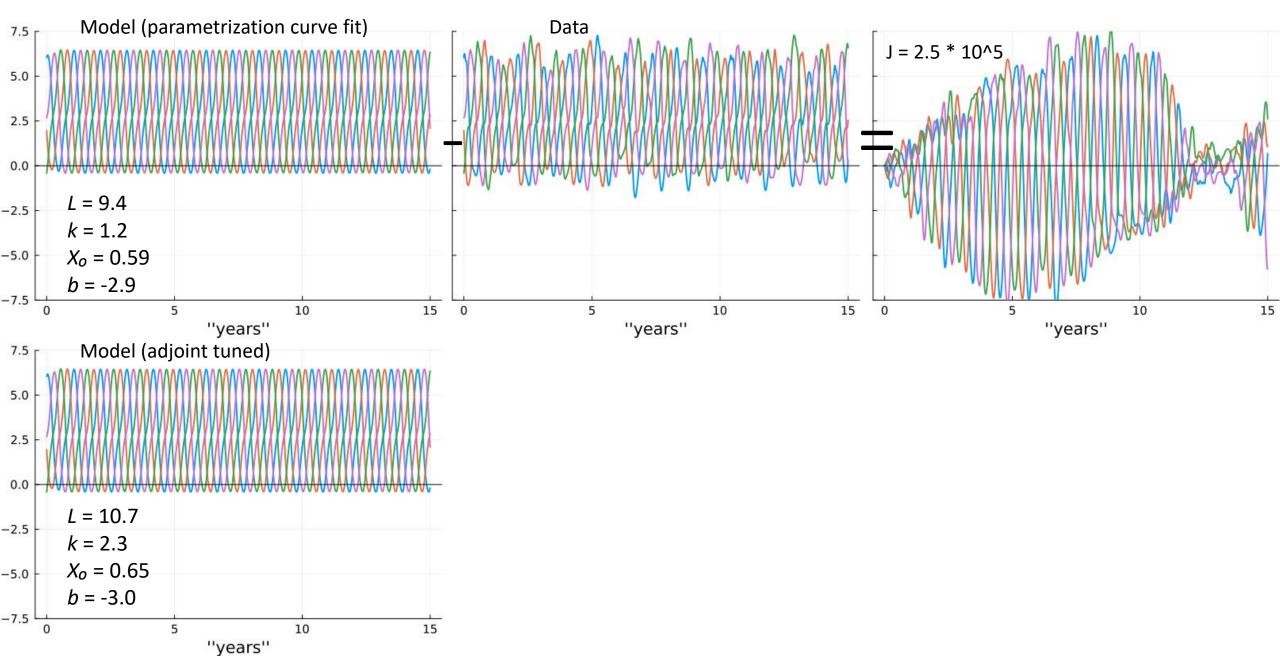
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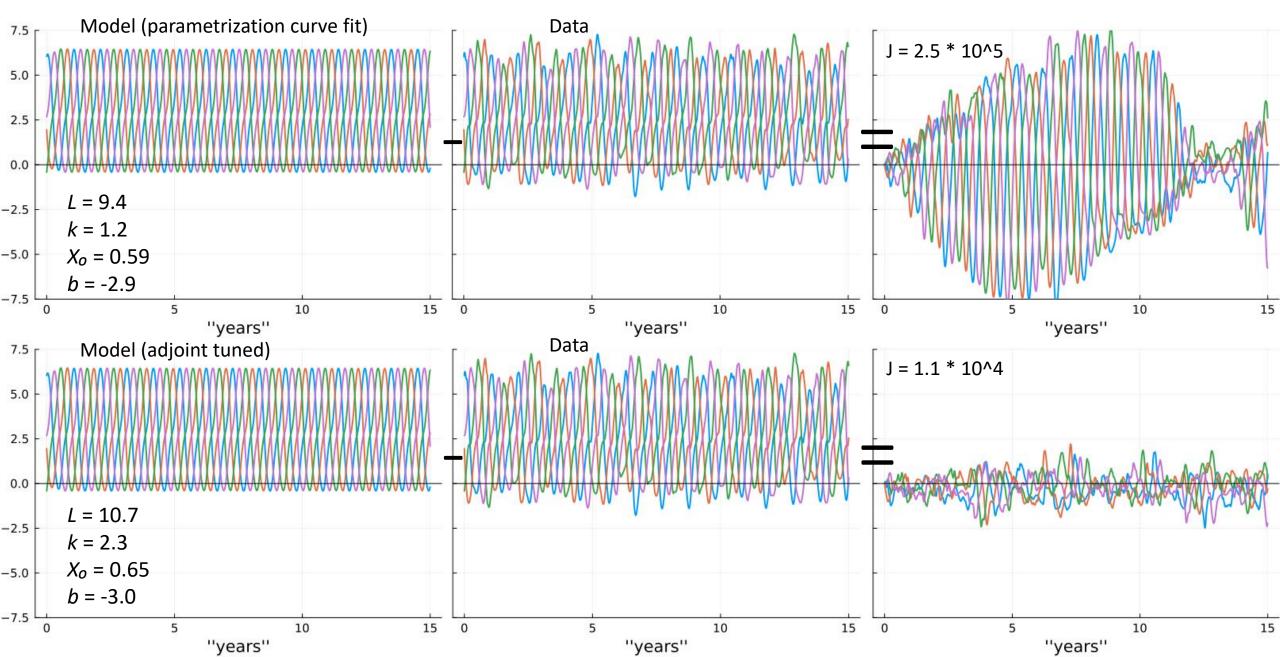
- L = 9.4
- k = 1.2
- $X_0 = 0.59$
- b = -2.9





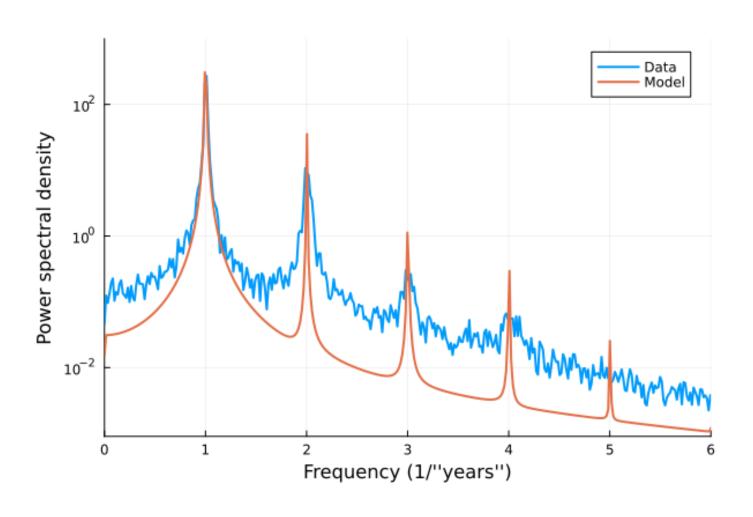






# What about statistics?

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$$\frac{dX_k^*}{dt} = -X_{k-1}^* \left( X_{k-2}^* - X_{k+1}^* \right) - X_k^* + F + U_p \left( X_k^* \right) \; ; \quad k = 1, ..., K$$

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$$U_{\text{det}}\left(X^{*}\right) = \frac{L}{1 + e^{-k(X^{*} - X_{0})}} + b$$

Stochastic: 
$$U_p\left(X^*\right) = U_{\text{det}}\left(X^*\right) + e(t)$$

$$e(t) = \phi e(t - \Delta t) + \sigma \sqrt{1 - \phi^2} z(t)$$

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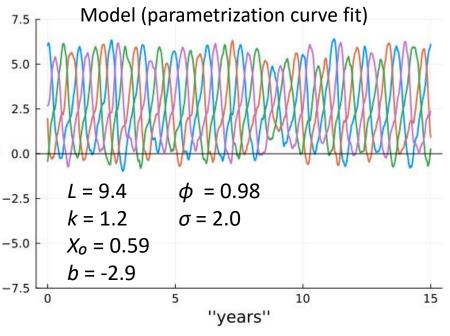
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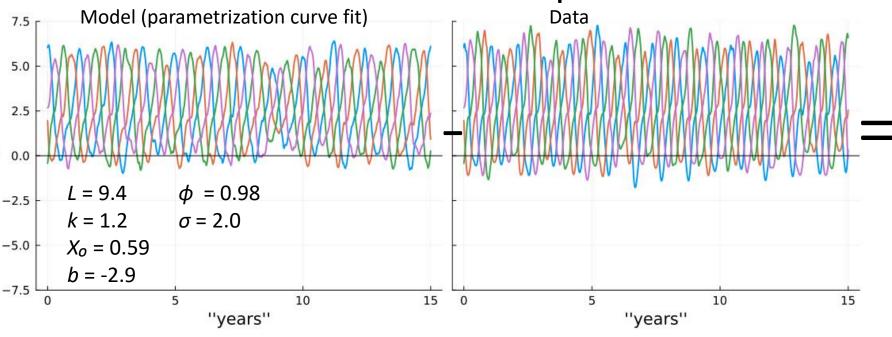
$$e(t) = \phi e(t - \Delta t) + \sigma \sqrt{1 - \phi^2} z(t)$$

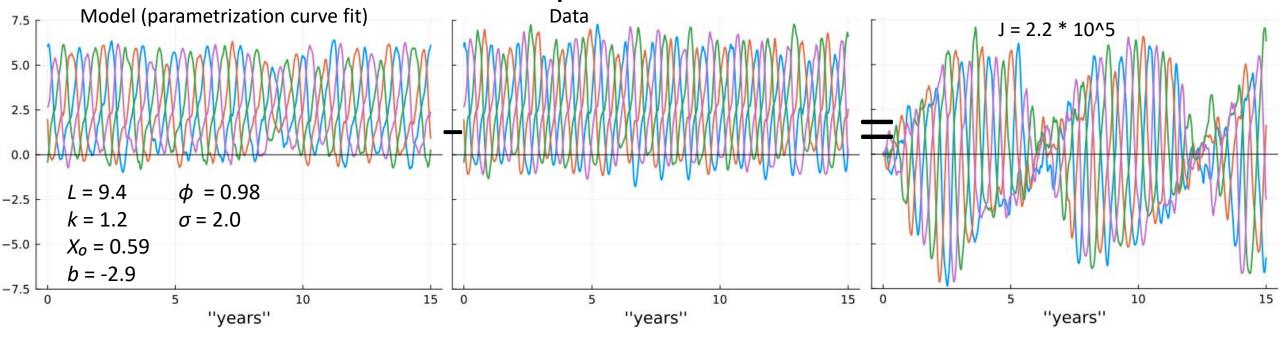
lag-1 autocorrelation

SD of *U* residual

unit variance Gaussian white noise





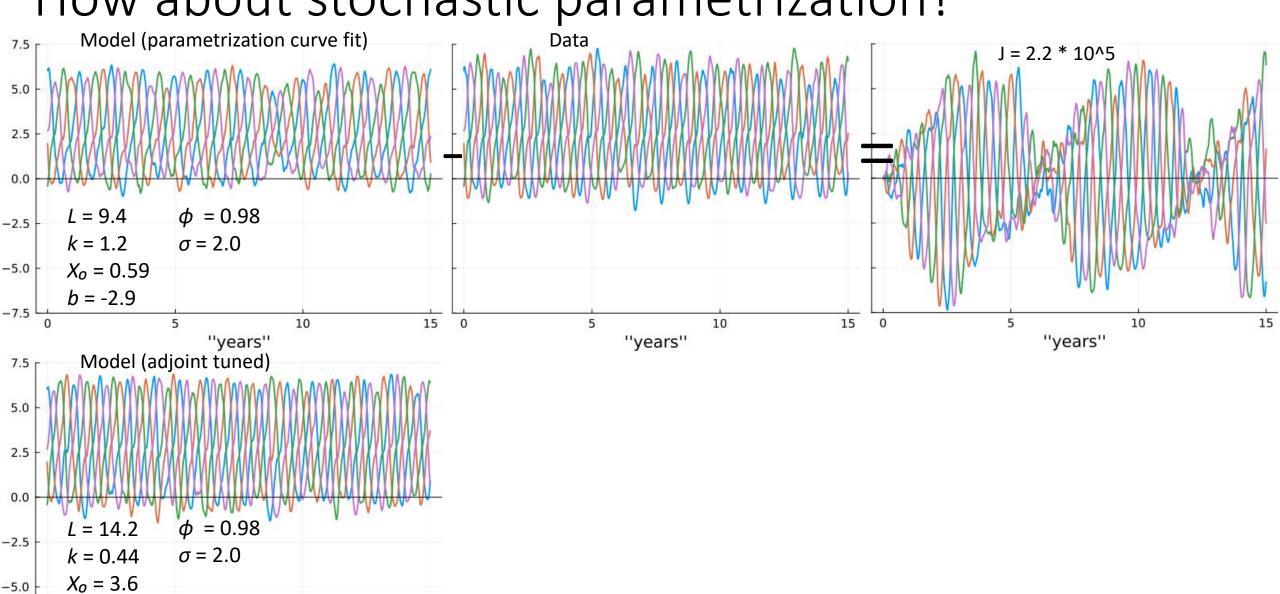


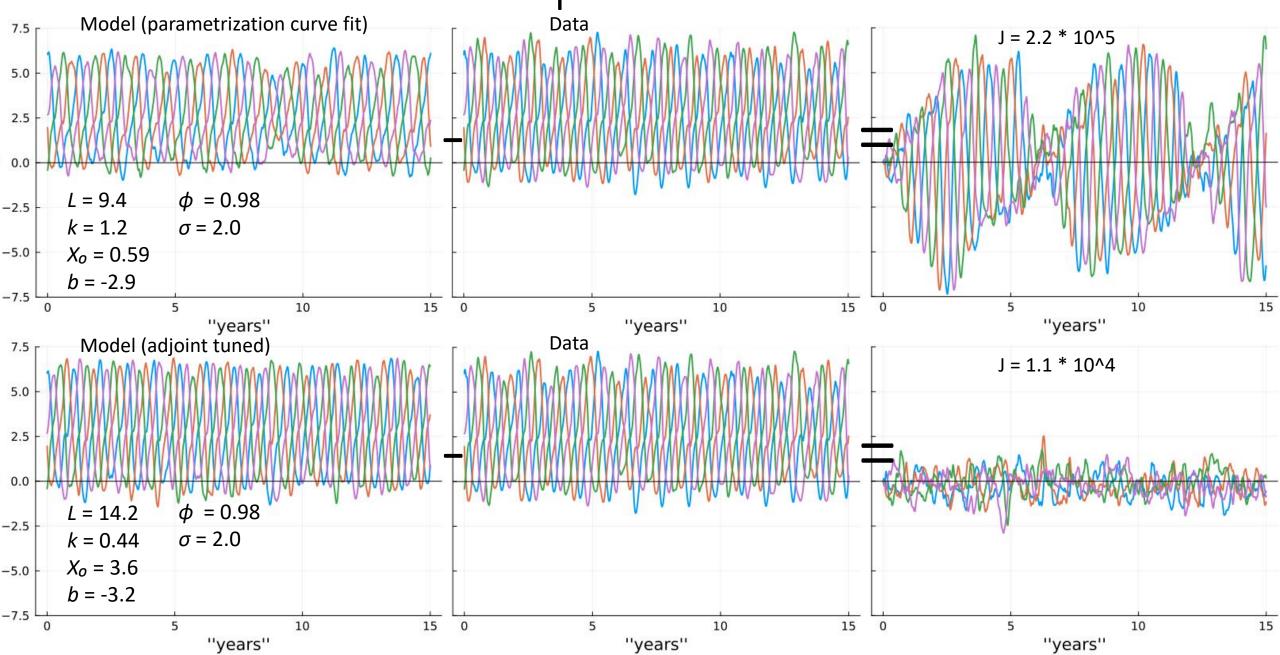
b = -3.2

10

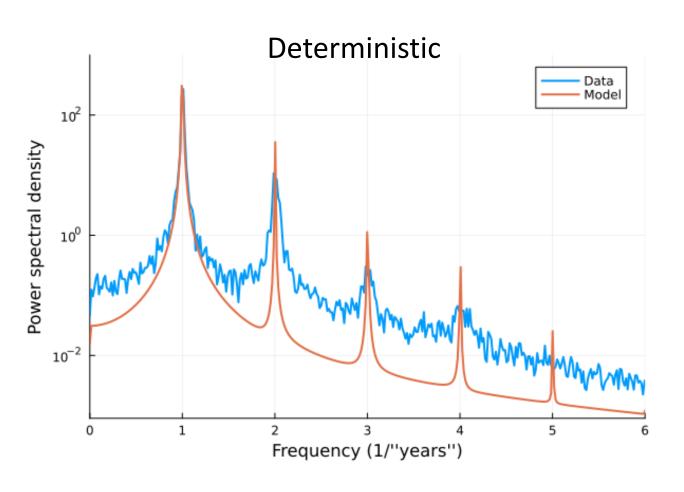
"years"

15

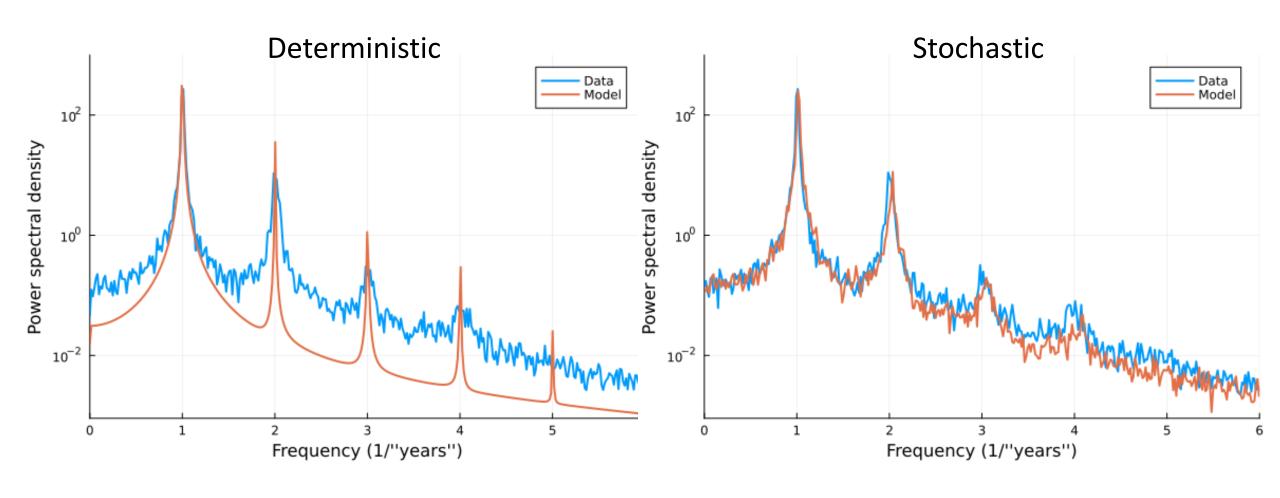




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# A look ahead

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- Further explorations in L96
  - Uncertainty quantification
  - Stability
  - Forecast skill
  - PSD misfit in cost function?

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  - Uncertainty quantification
  - Stability
  - Forecast skill
  - Adjoint tuned statistics? PSD misfit in cost function?
- Idealized MITgcm setups
  - Baroclinic gyre with eddy parametrization
  - soma (MPAS-Ocean ideal model with continental shelf)

